

## ESC setup manual

For detailed APP instructions please visit <u>www.corsatec.info</u>



### **User Safety guidelines:**

This product is designed specifically for professional racing and should be used exclusively by expert racers. To ensure the safety of both children and adults, please exercise caution and adhere to the following guidelines:

- 1. After each use, make sure to turn off the Electronic Speed Controller (ESC) and disconnect the battery.
- 2. Avoid storing the vehicle or ESC with the battery wires connected.
- 3. In the event of excessive ESC overheating, cease driving or using the device immediately and disconnect the battery as soon as possible.
- 4. When installing power wires, pay close attention to the A-B-C wire sequence on the ESC and motor, and connect them accordingly.
- 5. Be mindful of the battery and ESC polarity. Do not connect the positive (+) and negative (-) battery wires incorrectly, as doing so may cause permanent damage to the ESC.
- 6. **CORSATEC** cannot be held liable for any damage resulting from improper use of this product.
- 7. This product is not waterproof so damage caused due to exposure to water or humidity is not covered.
- 8. Any damage caused due to wrong installation and excessive vibration is also not covered.

### Installation and startup guidance

IMPORTANT NOTICE: For the CT30004 1/8 300A Electronic Speed Controller (ESC), the sensorless mode can be utilized without any disruptions, providing exceptional throttle response. Kindly read and adhere to the following cautions and warnings before usage.

### **Power On/Off Instructions:**

- 1. To power on the ESC, briefly press the power button.
- 2. To power off the ESC, press and hold the power button.
- 3. Be sure to disconnect the battery immediately after powering off the ESC.

### **Throttle/ESC Calibration Procedure:**

Please refer to below text, or/and below visual explanation of the procedure. If you are not sure or experience any difficulties, please refer to the video on <a href="https://www.corsatec.info">www.corsatec.info</a> from our Top Driver David Ronnefalk.

- 1. Activate your transmitter/radio and then connect the battery to the ESC.
- 2. Press and hold the power button until the LED indicator turns **solid blue** and the motor emits a long beep.
- 3. Release the button; the LED will turn solid red, indicating calibration mode.
- 4. Move the throttle trigger to the full throttle position. The blue LED will blink three times and the motor will beep once, confirming that the full throttle position has been saved.

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- 5. Move the throttle trigger to the full brake position. The blue LED will blink three times and the motor will beep twice, confirming that the full brake position has been saved.
- 6. Return the throttle trigger to the neutral position. The blue LED will blink three times and the motor will beep three times, signifying that the throttle calibration has been completed. Turn off the ESC.
- 7. When you power on the ESC again, it will be calibrated and ready for use.

### **IMPORTANT Firmware Upgrade notification**









Before using the ESC in competition Racing, install the app following the above QR code, and update the ESC with the latest firmware to maximize performance and reliability of the ESC. We constantly improve the performance of the ESC integrating new input from our professional Racing Team.

- 1. In the event of a failed ESC firmware upgrade, please restart the ESC and ensure that the firmware is upgraded through the APP once more. Note that all other functions remain inaccessible until the successful completion of the firmware upgrade.
- 2. During firmware upgrade mode, the ESC will display a faintly blinking Red LED, while a faintly blinking Blue LED indicates data transmission is taking place.
- 3. It is crucial not to turn off the ESC while the firmware upgrade process is ongoing. The ESC can be switched off only after pressing the power button for approximately 5 seconds.

### **Bluetooth Connectivity**

- 1. Reset Password: To restore the default Bluetooth password (0000), turn on the ESC and hold the power button for roughly 10 seconds.
- 2. Utilizing Bluetooth, users can connect to the CORSATEC app for programming parameters, upgrading firmware, and checking real-time ESC data.
- 3. Please be aware that the operational range of Bluetooth is approximately 10 meters, which may be affected by the presence of metals, strong interference signals, or physical obstacles.
- 4. The Bluetooth name cannot be modified.
- 5. Bluetooth connections will fail during the ESC throttle calibration process.

### **Real-Time Data**

- 1. Real-time data is only accessible when the ESC receives a throttle signal.
- 2. Please note that the real-time data is intended for reference purposes, with an accuracy margin of ±10%. For more accurate measurement, the use of professional equipment is recommended.
- 3. For a detailed description of real-time data items please note last table on page 4.







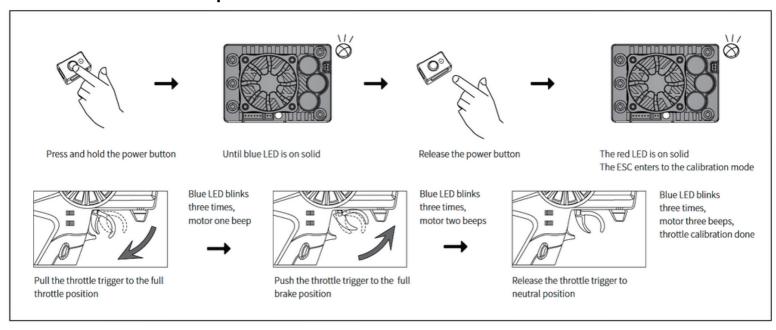
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### **ESC LED indications and warnings**

Upon activation of any protective measure, the RED LED will remain steadily illuminated once the power button is pressed.

- 1. A single, recurring flash of the RED LED at one-second intervals, appearing as "x = x," signifies an abnormal voltage reading.
- 2. A double flash of the RED LED at one-second intervals, appearing as "¤¤ ¤¤," indicates that the ESC temperature reading is abnormal.
- 3. An alternating single and double flash of the RED LED at one-second intervals, appearing as "x xx x xx," demonstrates simultaneous abnormal voltage and temperature readings.
- 4. In the absence of any detected signal, the RED LED will not respond or provide any indication, even if there are abnormal voltage or temperature readings.
- 5. A double flash of the BLUE LED at two-second intervals, appearing as "¤¤ ¤¤," signifies an abnormal throttle reading. This may be due to a missing throttle signal and/or the throttle not being in a neutral position.

## please check below the visual references



### LED Status

During operation

| Throttle Position | Blue LED | Red LED |  |
|-------------------|----------|---------|--|
| Neutral           | Blinking | OFF     |  |
| Full Throttle     | ON       | ON      |  |
| Full Brake        | OFF      | ON      |  |

Note: When you pull the throttle from neutral position to full throttle position, the Blue LED will blink, and the blink frequency will go faster when the throttlegoes higher.

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# **ESC setup manual**

| Troubleshoot Master File CORSATEC RS Series  |   |  |  |
|--|---|--|--|
| Observation                                  | Possible causes   | Solution   |  |
| ESC unable to startup, no reaction           | Switch error BEC cable not connected correctly Observe if cross connection (reverse polarity) has appeared  | Switch damage, contact CORSATEC dealer and replace<br>Check connection and cable position  Send ESC to CORSATEC dealer and repair  |  |
| Loss of power, stuttering, no start of motor | Motor magnet is damaged Motor connection is poor Low Voltage protection mode (refer to LED flash indications) ESC component malfunction (crash/water) | Contact CORSATEC dealer for replacement magnet Check connections and resolder Check battery quality and V (adjust LV protection setting) Contact CORSATEC dealer and repair  |  |
| Motor runs backwards                         | ABC connection incorrect  Radio setting incorrect   | Change ABC setting in APP, or cross 2 of ABC wires<br>EPA FW or REV/BRAKE is not at 100%, neutral trim<br>setting<br>Follow the instruction how to calibrate (make sure 100% |  |
|  | Calibration incorrect/not finished  | EPA)   |  |

If you have carefully checked and observed all possible above causes while the ESC/and or motor still malfunctions, please inquire support@corsatec.net and send below:

- 1) Detailed description of your observation/problem
- 2) A picture of the ESC while installed in the car
- 3) Add a video showing the issue you observe, maximum 30 seconds, or a link where we can observe/download

Our highly experienced support Team will come back to you ASAP; please note that due to time zone differences the reply could take longer as expected

Thank you for your patience and trust using CORSATEC Racing Products

| Data logging understanding |                 |   |  |
|----------------------------|-----------------|---|--|
|                            | Item            | Description   |  |
| 1                          | Input Throttle  | Throttle input from the receiver to ESC               |  |
| 2                          | Output Throttle | Throttle output from the ESC to the motor             |  |
| 3                          | Voltage min     | Battery voltage monitored by the ESC                  |  |
| 4                          | Voltage max     | Minimum voltage detected by the ESC.                  |  |
| 5                          | Temperature     | ESC temperature.                                      |  |
| 6                          | Max Temperature | Maximum recorded temperature by the ESC               |  |
| 7                          | RPM             | Motor revolutions per minute (RPM)                    |  |
| 8                          | Max RPM         | Maximum RPM detected by ESC                           |  |
| 9                          | Advance Timing  | The cumulative ESC timing, including Boost and Turbo. |  |



| APP commands       | Values  | Effect  |
|--------------------|---------|---|
| POWER CONTROL      | -       |   |
| 1st division limit | 0/100%  | Dividing of the power curve; zero to value sector 1 (for example, 0-30%)  |
| 2nd division limit | 0/100%  | Dividing of the power curve; set value sector 1 to value sector 2 (for example, 30-70%)   |
| 1st activation     | 0.1/3ms | Power delivery response (acceleration feeling) 1st sector. The lower the value, the response increases (faster) Recommended range 0.3/1ms                               |
| 2nd activation     | 0.1/3ms | Power delivery response (acceleration feeling) 2nd sector. The lower the value, the response increases (faster) Recommended range 0.3/1ms                               |
| 3rd activation     | 0.1/3ms | Power delivery response (acceleration feeling) 3rd sector (from value set 2nd division to 100%). The lower the value, the response increases (faster) Recommended range |
| min throttle       | 2/16%   | 0.3/1ms Throttle sensitivity from neutral point. Recommended setting is default   |
| neutral range      | 3/12%   | Width of neutral setting. This to widen in case of "sensitive finger" or extreme fast servo movement  |
| coast              | 0/30%   | Off power delay (when throttle is released). More coast > roll more free when "reduce power"  |
| neutral coast      | On/Off  | Off power delay (when throttle is released to neutral immediately). More coast > roll more free when "off power in neutral position"                                    |
| power force        | 50/100% | Maximum power delivered by esc. In slippery conditions we suggest 85-90%  |
| reverse force      | 50/100% | Maximum power delivered by esc when reverse power is activated (only active when the running mode is set to FBR)  |

#### BRAKE CONTROL

| BRAKE CONTROL       |           |   |
|---------------------|-----------|---|
| division limit      | 0/100%    | Dividing of the brake force curve; zero to value sector 1 (for example, 0-30%)  |
| 1st activation      | 0,1/3ms   | Brake delivery response (brake feeling) 1st sector. The lower the value, the reponse increases (faster) Recommended range 0.3/1ms |
| 2nd activation      | 0,1/3ms   | Brake delivery response (brake feeling) 2nd sector. The lower the value, the reponse increases (faster) Recommended range 0.3/1ms |
| pwm freq            | 0,1/16khz | Brake feeling frequency. Normally, by lowering the value the response increases (more aggressive). 1/4 khz is adviced range       |
| min brake force     | 0/50      | Minimum setting before ESC initiates brake  |
| max brake force     | 10/100    | Maximum brake force setting   |
| drag brake force    | 0/100%    | Brake force when throttle is at neutral position: max value recommended 10%   |
| drag brake response | 0,1/3ms   | Time delay to drag brake activation (lower is faster response)  |

#### TURBO SETTING

| 101.00 22111110 |           |  |
|-----------------|-----------|--|
| turbo timing    | 0/64      | Turbo activation point (only with sensor attached). Increases top speed, but decreases runtime and increases motor temperature |
| delay           | 0/2s      | Time delay of turbo activation   |
| angle inc rate  | 1/64/0,1s | Value (force) of turbo activation. max value recommendation is 4deg  |
| angle dec rate  | 1/64/0,1s | Value (force) of turbo de-activation. max value recommendation is 4deg. A different rate will lead to faster responses         |

#### ESC SET UP

| running mode    |                | Forward/brake is common racing mode, however FBR (forward brake reverse) works fine too.   |
|-----------------|----------------|--|
| motor rotation  | CC-CCW         | CW = clockwise, CCW = counter clock wise   |
| motor pole      | 2 to 8 poles   | Motor pole setting. 4P is most commonly used setting for 1/8 buggy or GT, check the motor manual specs in case not sure.   |
| bec output      | 6/7.4v         | Voltage delivered to servo (more V make servo faster/stronger)   |
| cut off voltage | 0 to 3.9v/cell | Battery cell cut off voltage, recommended is 3.2V/cell. Lower is Ok but might lead to battery damage if low C/high cycle life batteries are used (case swelling) |
| drive pwm freq  | 1 to 32khz     | Highest setting is smoothest power delivery. MIN set up adviced 8KHZ   |
| button off      | 0.5 to 4s      | Time delay to switch off ESC while holding the push button (recommend 1 second)  |
| race rule       | IFMAR/ROAR     | ROAR mode to be used to disactivate the bluetooth connection. Once activated, unplug the receiver plug and reconnect to reactivate the BT                        |



